

# **DEVELOPMENT AND EVALUATION OF DENSIFICATION MODELS FOR Al-Pb ALLOYS PRODUCED BY POWDER METALLURGY**

### **\*Ch V S H S R Sastry<sup>1</sup> , G Ranga Janardhana<sup>2</sup>**

<sup>1</sup>Department of Mechanical Engineering, Kakatiya Institute of Technology and Science, Warangal, Andar Pradesh-506015, India <sup>2</sup>Department of Mechanical Engineering, JNT University College of Engineering, Kakinada, Andar Pradesh-500072, India

## **ABSTRACT**

 The recent research into the alternate sliding bearing materials unequivocally point to the beneficial role of lead (Pb) in aluminum (Al). But, these alloys offer a manufacturing challenge, due to wide immiscibility gap. For such applications, apart from homogeneous microstructure, porosity control is also equally important, as it influences the tribological performance through spreading of lead in aluminum matrix. These objectives can be achieved together by mechanical alloying through powder metallurgy (P/M). However, die compaction in P/M results in inhomogeneous density distributions leading to distortion during sintering process. In order to control the shape of final P/M parts, the appropriate models are necessary for densification of composite powders to simulate cold compaction responses. In the present work, the authors studied the effect of alloy composition and ball to charge ratio on densification behaviour of conventional ball milled Al-Pb alloys, with a view to develop non-linear regression models that can best describe the densification behaviour of ball milled Al-Pb alloys from compressibility test data. Based on their validation, the study concludes that Richards model effectively predicts densification behaviour of P/M processed Al-Pb alloys. Such modeling will be of great significance in simulating the cold compaction response, especially in case of alloys where no historical data exists regarding effect of processing conditions on densification behaviour.

**Key words:** *Al-Pb Alloys, Compressibility Test, Densification Modeling, Powder Metallurgy.*

### **1. Introduction**

In the manufacturing technologies of P/M products, die compaction is widely used. However, P/M parts formed by die compaction have inhomogeneous density distributions due to the friction between the powder and the die well. Inhomogeneity in density leads to non-uniform shrinkage or distortion during sintering process, and thus makes it difficult to control the shape of final P/M parts [1]. In order to control the shape of final P/M parts, the appropriate models are necessary for densification of composite powders to simulate cold compaction responses. Theories describing the deformation of porous material are enumerated and the changes in density in powder forming process are analyzed with the help of a theoretical and numerical analysis by Bruhns and Sluzalec [2] to model the densification behaviour of porous materials.

A number of yield functions have been developed for densification behaviour of metal powder, so far. Kuhn and Downey [3], Shima and Oyane [4], and Doraivelue et al [5] proposed yield functions based on uniaxial tests on sintered powder compacts. Brown and Weber [6], however, showed that densification behaviour of loose powder is different from that of sintered powder

in uniaxial tests. The discrepancy in densification behaviour is more important, in the early stage of compaction, because the inter-particle cohesion of loose powder compact is much lower than that of a sintered powder compact. Thus, these models [3-5] may not be appropriate for the early stage of compaction response. A macroscopic constitutive model from particle deformations was proposed by Fleck et al. [7]. However, this yield function did not agree well with experimental data of soft metal powder during die compaction [8].

 A number of researchers also adopted models, for densification of metal powder from soil mechanics. These models include Drucker-prager model [9], camclay model [10], and cap models. Out of them, the cap model may be useful to predict densification behaviour of loose soft metal powder in all stages of compaction, because this model based on experimental data of lose powder incorporates densification due to inter-particle movements as well as particle's plastic deformation.

 The hyperbolic cap model proposed by Lee and Kim [1] agreed well with the experimental data in the overall density region under cold compaction of Aluminum alloy powder. Whereas the finite element

 *\*Corresponding Author - E- mail: sastry.challa3@gmail.com*

based models such as Shima –Oyane model and other models underestimated the experimental data in the low density region and in the high density region respectively. In view of the limitations in the existing densification models [2-10] an attempt is made in this work, to apply the techniques of non-linear regression models, for the experimental data generated on Al-Pb alloys.

### **2. Experimental Details**

The Al and Pb powders of various compositions, shown in Table 1 are used in the present work. Their particle distributions are presented in Figure 1(a) and Figure 1 (b). These metal powders are mixed in conventional ball mill operated at 200 RPM.





**Fig. 1(a) Particle Size Distribution of Al Powder**



**Fig. 1(b) Particle Size Distribution of Pb Powder**

Samples are withdrawn from the ball mill after 45 min. of continuous run and subjected to compressibility test. The compressibility test is carried out on a hydraulic press using one set of die and punches

that conform to cylindrical shape of test sample with 1 inch diameter. For the purpose of compressibility test, the lower punch is inserted into the die and the assembly is placed on the lower platen of the hydraulic press. Using supporting spacers which may be wooden blocks, the die is raised so that the depth of powder fill will be proper to give a green compact height equal to the compact diameter  $+$  or  $-$  10%. The powder depth varies with the particular powder used, and was determined empirically. Sufficient quantity of alloy powder is poured into the die cavity to fill it to overflowing. Then, the powder is leveled off flush with the top of the die by passing the straight edge of the spatula horizontally across the die top. The die is tapped a little to make the powder level settle slightly below the die top. The upper punch is positioned so that it rests in the die and on top of the powder. A preliminary force of 0.2 Kgf is applied and then removed, after which the spacers are removed. Then, a force of 500Kgf is applied, building up to this amount at a constant rate of loading. The applied force is gradually withdrawn and the green compact is ejected by use of a die push – down spacer placed between the die top and the bottom of the platen above it. Subsequently, the height of the green compact is measured, to calculate the volume of the green compact. The weight of the compact is determined to the nearest 0.001 gram, to calculate the green density of the compact. These steps are repeated, using appropriately larger amounts of powder and final compacting forces of 1,000, 1,500, 2,000, 2,500, 3,000, 3,500, 4,000, 4500 kgf etc. The compressibility test results of Al-Pb alloys are shown in Table 2.

## **3. Modeling of Densification Behavior**

### **3.1 Model selection**

Given a set of data points, from the compressibility test, the data is fitted to a model in the form of a parametric equation. One important consideration in selecting an appropriate model is the underlying law that the data represents. Optimally, the model should be chosen to reflect that law so that the parameters in the curve fit have physical interpretation and meaning. In the work presented here, the nonlinear models known as the sigmoidal family models are selected based on the nature of the experimental data.

 The sigmoidal or "S-shaped" growth curves (namely Gompertz Model, Logistic Model, Richards Model, MMF Model and Weibull Model) start at a fixed point and increase their growth rate monotonically to reach an inflection point. After this, the growth rate approaches a final value asymptotically. These five models are fitted to the experimental data pertaining to various compositions of Al-Pb alloys made by

conventional ball milling, at two different ball to charge ratios. The ball to charge ratios used in the experiments are selected based on general engineering practice for such applications as well as the volume capacity of the attrition mill.

### **3.2 Solution methodology**

This program uses the Levenberg-Marquardt method to solve nonlinear regression. This method combines the steepest-descent method and a Taylor series based method to obtain a fast, reliable technique for nonlinear optimization. The Levenberg-Marquardt (LM) algorithm allows for a smooth transition between these two methods as the iteration proceeds. In general, the data modeling equation (with one independent variable) can be written as follows:

$$
Y=Y(x, \bar{a})\tag{1}
$$

The above expression simply states that the dependent variable y can be expressed as a function of the independent variable x and vector of parameters a of arbitrary length. Note that using the ML method, any nonlinear equation with an arbitrary number of parameters can be used as the data modeling equation. Then, the "merit function" we are trying to minimize is

$$
\chi^{2}(\bar{\mathbf{a}}) = \sum_{i=1}^{N} \left[ \left( Y_{i} - Y(X_{i}, \bar{\mathbf{a}}) \right) / \sigma_{i} \right]^{2}
$$
 (2)

Where N is the number of data points, xi denotes the x data points, yi denotes the y data points,  $\sigma_i$ is the standard deviation (uncertainty) at point i, and  $y(xi,a)$  is an arbitrary nonlinear model evaluated at the  $i<sub>th</sub>$ data point. This merit function simply measures the agreement between the data points and the parametric model; a smaller value for the merit function denotes better agreement. This merit function is also called as the chi-square. The Taylor series method states that sufficiently close to the minimum, the function can be approximated as a quadratic. Without detailed approximated as a quadratic. explanation of that method, a step from the current parameters  $\bar{a}_{\text{cur}}$  to the best parameters  $\bar{a}_{\text{min}}$  can be to the best parameters  $\bar{a}$  min can be written as

$$
\bar{\mathbf{a}}_{min} = \bar{\mathbf{a}}_{cur} + \mathbf{H}^{-1} \left[ -\nabla \chi^2 \left( \bar{\mathbf{a}}_{cur} \right) \right] \tag{3}
$$

Where H is the Hessian matrix (a matrix of second derivatives). If the approximation of the function as a quadratic is a poor one, then we might instead use the steepest-descent method, where a step to the best parameters from the current parameters is

$$
\bar{\mathbf{a}}_{\min} = \bar{\mathbf{a}}_{\text{cur}} - \mathbf{C} \nabla \chi^2 (\bar{\mathbf{a}}_{\text{cur}})
$$
 (4)

This equation simply states that the next guess for the parameters is a step down the gradient of the merit function. The constant C is forced to be small enough that a small step is taken and the gradient is accurate in the region that the step is taken.

Since we know the chi-square function, we can directly differentiate to obtain the gradient vector and the Hessian matrix. Taking the partial derivatives of the merit function with respect to a gives

$$
\frac{\partial \chi^2}{\partial a_k} = -2 \sum_{i=1}^N \left[ \frac{Y_i - Y(x_i; \bar{a})}{\sigma_i^2} \right] \cdot \frac{\partial Y(x_i; \bar{a})}{\partial a_k} \qquad (5)
$$

To obtain the Hessian matrix, take the gradient of the gradient above (so that we have a matrix of partial second derivatives)

$$
\frac{\partial \chi_2}{\partial a_k \partial a_l} \frac{N}{i=1} \frac{\partial Y(x_i; \bar{a})}{\sigma_i^2} \frac{\partial Y(x_i; \bar{a})}{\partial a_k} \frac{Y_i - Y(x_i; \bar{a})}{\sigma_i^2} \frac{\partial^2 Y(x_i; \bar{a})}{\partial a_k \partial a_l} \frac{1}{\sigma_i^2}
$$

 $(6)$ 

Now, for convenience, define the gradient vector and the curvature matrix as

$$
G_{K} = \frac{1}{2} \frac{\partial \chi 2}{\partial a_{k}} = \sum_{i=1}^{N} \left[ \frac{Y_{i} - Y(x_{i}; \bar{a})}{\sigma_{i}^{2}} \cdot \frac{\partial Y(x_{i}; \bar{a})}{\partial a_{k}} \right] \qquad (7)
$$

$$
Ckl = \frac{\partial^2 \chi 2}{\partial a_{k} \partial a_{l}} = \sum_{i=1}^{N} \left[ \frac{1}{\sigma_i} \cdot \frac{\partial Y(x_i; \bar{a})}{\partial a_{k}} \cdot \frac{\partial Y(x_i; \bar{a})}{\partial a_{l}} \right]
$$
(8)

<b>Pressure</b>	Density $(Gr/Cm^3)$									
Mpa	95Al-5Pb		90Al-10Pb		85Al-15Pb		80Al-20Pb		75Al-25Pb	
	alloys		alloys		alloys		alloys		alloys	
	<b>BCR</b>	<b>BCR</b>	<b>BCR</b>	<b>BCR</b>	<b>BCR</b>	<b>BCR</b>	<b>BCR</b>	<b>BCR</b>	<b>BCR</b>	<b>BCR</b>
	$= 5:1$	$=10:1$	$= 5:1$	$=10:1$	$= 5:1$	$=10:1$	$= 5:1$	$=10:1$	$= 5:1$	$= 10:1$
10	1.312	1.575	1.669	1.673	1.752	1.735	1.865	1.804	1.808	1.988
20	1.389	1.60	1.713	1.730	1.807	1.779	1.932	1.886	1.839	2.054
30	1.425	1.629	1.754	1.784	1.847	1.851	1.990	1.964	1.979	2.103
40	1.498	1.677	1.819	1.856	1.945	1.928	2.046	2.028	2.015	2.162
50	1.538	1.738	1.872	1.918	2.011	2.003	2.099	2.097	2.103	2.259
60	1.605	1.798	1.947	1.992	2.052	2.048	2.168	2.204	2.174	2.335
70	1.649	1.851	1.993	2.037	2.106	2.135	2.226	2.273	2.25	2.406
80	1.699	1.89	2.05	2.103	2.179	2.203	2.293	2.327	2.307	2.472
90	1.715	1.949	2.105	2.152	2.237	2.25	2.348	2.386	2.361	2.541
100	1.765	2.034	2.155	2.146	2.287	2.323	2.401	2.455	2.429	2.589
110	1.809	2.039	2.189	2.269	2.319	2.363	2.489	2.491	2.492	2.637
120	1.867	2.059	2.264	2.292	2.372	2.413	2.559	2.541	2.571	2.677

**Table 2: Compressibility test results of conventional ball milled Al-Pb alloys**

**Table 3: A Comparison of Densification Models for Ball milled Al-Pb Alloys** 

Sl.No.	<b>Alloy</b> composition	<b>Densification Model</b>	<b>Coefficients</b>	<b>Standard</b> error(S)	<b>Coefficient of</b> correlation (r)	<b>Comments</b>
1.	95Al-5Pb (ball to charge $ratio=5:1$ )	Gompertz Relation: $y=a*exp(-exp(b-cx))$	$a = 2.384449,$ $b = -0.446123$ , $c = 0.00774622$	0.01196878	0.99809979	The fit converged to a tolerance of 1e-006 in 30 iterations. No weighting used
		Logistic Model: $y=a/(1+b*exp(-cx))$	$a = 2.2470045$ , $b = 0.7827956$ , $c = 0.0108170$	0.0122433	0.9980115	The fit converged to a tolerance of 1e-006 in 12 iterations. No weighting used
		<b>MMF</b> Model: $y=(a^*b+c^*x^{\wedge}d)/(b+x^{\wedge}d)$	$a = 1.233188$ , $b = 411.95285$ , $c = 5.8028301.$	0.0121162	0.9982692	The fit converged to a tolerance of 1e-006 in 26 iterations. No weighting used.
		Weibull Model: $y=a-b*exp(-c*x\Delta d)$	$a = 3.0046159$ , $b = 1.7624897$ , $c = 0.0049914$ , $d = 0.9286785$	0.0122362,	0.9982347,	The fit converged to a tolerance of 1e-006 in 100 iterations. No weighting used.
2.	95Al-5Pb (ball to charge ratio= $10:1$ )	Logistic Model: $y=a/(1+b*exp(-cx))$	$a = 3.4394767$ , $b = 1.2909257$ , $c = 0.0057404523$	0.0215148	0.9939606	The fit converged to a tolerance of 1e-006 in 55 iterations. No weighting used.
		Richards Model: $y=a/(1+exp(b-cx)^{1/(1/d)})$	$a = 2.052706$ , $b = 39.213857$ , $c = 0.3657327$ , $d = 126.89219$	0.0153676	0.9972656	The fit converged to a tolerance of 1e-006 in 23 iterations. No weighting used.
3.	90Al-10Pb (ball to charge $ratio=5:1)$	Logistic Model: $y=a/(1+b*exp(-cx))$	$a = 3.5803115$ , $b = 1.2340121$ , $c = 0.00621108$	0.0103343	0.9988791	The fit converged to a tolerance of 1e-006 in 51 iterations. No weighting used.
		Richards Model: $y=a/(1+exp(b-cx)^{1}/(1/d))$	$a = 2.502839$ , $b = 4.1727808$ , $c = 0.0303377$ , $d = 9.4789474$	0.0104810,	0.9989752,	The fit converged to a tolerance of 1e-006 in 18 iterations. No weighting used
4.	90Al-10Pb (ball to charge $ratio=10:1)$	<b>Gompertz Relation:</b> $y=a*exp(-exp(b-cx))$	$a = 3.1580973$ , $b = -0.3842547$ , $c = 0.0062701$	0.0201725	0.9960780	The fit converged to a tolerance of 1e-006 in 48 iterations. No weighting used.









### **Table 5: Validation of Richards Model-Stage-I (a) Conventional Ball Milled 95Al-5Pb Alloys**





## **(c) Conventional Ball Milled 80Al-20Pb Alloys**



## **(d) Conventional Ball Milled 75Al-25Pb Alloys**



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Table 6: Validation of Richards Model -Stage-II									
	Density $(Gr/Cm^3)$								
<b>Compaction</b> Pressure(MPa)	<b>Experimental</b>	Value predicted by	$\frac{0}{0}$	Value predicted	$\frac{0}{0}$				
	value	Hyperbolic cap model by Lee and Kim	<b>Deviation</b>	by Richards model	<b>Deviation</b>				
20	1.674	1.661	$-0.77658$	1.674	0.00000				
50	1.809	1.809	0.00000	1.807	$-0.11056$				
70	1.890	1.890	0.00000	1.891	0.05291				
100	1.998	2.025	1.35135	1.997	$-0.05005$				

It can be noted that the second derivative term in C will be ignored because of two reasons: it tends to be small because it is multiplied by (y-yi), and it tends to destabilize the algorithm for badly fitting models or data sets contaminated with outliers. This action in no way affects the minimum found by the algorithm; it only affects the route in getting there. So, the Taylor series method (inverse Hessian method) can be written as the following set of linear equations:

$$
\sum_{k=1}^{N_{P}} C_{kl} \delta_{al} = G_{k}
$$
 (9)

Where,  $N_P$  is the number of parameters in the model that is being optimized. This linear matrix will be our workhorse for this method after some modification; it can be solved for the increments  $\delta_a$  that, when added to the current approximation for the parameters, gives the next approximation. Likewise, we can substitute our "convenient" definitions into the steepest descent formula to obtain

$$
\delta_{\rm al}=c \cdot G_{\rm al} \tag{10}
$$

The steepest descent method works best far away from the minimum and the Taylor series method works best close to the minimum. The Levenberg-Marquardt (LM) algorithm allows for a smooth transition between these two methods as the iteration proceeds. The first issue in deriving the LM method is to attach some sort of scale to the constant c in the steepest-gradient method (equation 10). Typically, there is no obvious way to determine this number, even within an order of magnitude. However, in this case, we have access to the Hessian matrix; examining its members, we see that the scale on this constant must be 1/Cll. But, that still may be too large, so let's divide that scale by a non-dimensional factor (l) and plan on setting this much larger than one so that the step will be reduced (for safety and stability). The second issue to formulate the LM method is noting that the steepest-descent and

Taylor series methods may be combined if we define a new matrix  $M_{ij}$  by the following

$$
M_{ii} = C_{ii} (1+\lambda)
$$
  

$$
M_{ij} = C_{ij}, \quad i \neq j
$$

This matrix combines equations (9) and (10) into a convenient and compact form. So finally, we have a means of calculating the step  $\delta_a$  in the parameters by the following system of linear equations

$$
\begin{array}{l}\n\mathbf{Np} \\
\mathbf{\Sigma} \mathbf{M}_{\mathbf{k}\mathbf{l}} \cdot \mathbf{\delta}_{\mathbf{al}} = \mathbf{G}_{\mathbf{k}} \\
\mathbf{K} = 1\n\end{array} \tag{11}
$$

Note that when  $\lambda$  is large, the matrix M is forced to be diagonally dominant; consequently, the above equation is equivalent to the steepest descent method (equation 10). Conversely, when the parameter **λ** goes to zero, the above equation is equivalent to the Taylor series method (equation 9). So, **λ** is varied to switch between the two methods, continually calculating a parameter correction da that we apply to our most recent guess for the parameter vector. The steps that are taken in the LM algorithm are as follows

1. Compute  $\chi^2$ (a)

2. Pick a conservative value for  $\lambda$  (0.001)

3. Solve the linear equations (equation 3) for δa

4. Evaluate  $\chi^2(a+\delta a)$ 

5. If  $\chi^2(a+\delta a) \geq \chi^2(a)$ , increase  $\lambda$  by a factor (10) and go back to step [3].

6. If  $\chi^2(a+\delta a) < \chi^2(a)$ , decrease λ by a factor (10), correct the parameter vector by  $a=a+\delta a$ , and go back to step [3].

Iteration is stopped when  $|\chi(2(a+\delta a) - \chi(2(a)))|$  < tolerance. This tolerance is the value specified for regression convergence. The non-linear algorithm uses this number to determine whether or not it has converged on the correct modal parameters. The difference between the standard errors in two consecutive iterations must be smaller than this tolerance for the computation to terminate. The smaller the tolerance, the more accurate the parameters will be,

but the algorithm will take more time to converge. In this work, the value of tolerance considered is  $1 \mu m$ .

For the models under consideration, the Coefficients, Covariance, Residuals, Coefficient of correlation and Standard error of estimate are computed. The performance of a curve fit is judged by two quantities - the correlation coefficient and the standard error of the estimate. In general, the correlation coefficient will range from 0 to 1, with a value of 1 being the best. For the alloys under consideration, the converging mathematical models are tabulated, for ball milled Al-Pb alloys in Table 3**.** The best fitting mathematical models are compared for five compositions of Al-Pb alloys and at two ball to charge ratios (BCR), in Table 4, based on maximum value of coefficient of correlation and minimum value of standard error of estimate.

From the results presented in Table 4, it can be observed that Richards model emerged as the best fit model, for a good number of the ball milled alloys, satisfying maximum value of coefficient of correlation and minimum value of standard error of estimate.

## **4. Validation of Densification Model**

The best fitting densification model (i.e. Richards Model) is validated in two stages. In the first stage, validation is taken up by considering the data outside the range of experimentation, in the present study. The results of first stage validation are presented in Table 5(a) to (d). It can be observed from these tables, that in case of ball milled alloys, the deviation between model predicted values and experimental values of density varied from  $-0.7\%$  to 0.8%.

In the second stage, validation of Richards model is taken up by considering the experimental data generated from the presentations by Lee and Kim [1] on Aluminum alloys in cold compaction, under similar test conditions as the ones used in this work. The results obtained in this validation of Richards model are compared with the values predicted by the hyperbolic cap model developed by Lee and Kim. On the basis of the comparison shown in Table 6, it can be observed that the deviation between experimental values considered and predicted values due to Lee and Kim is in the range of -0.776% to 1.351%. Whereas the deviation observed with Richards model is in the range of -0.11% to 0.05%. This clearly demonstrates that for the composition of Al-Pb alloys and particle distribution considered in the present work, Richards model effectively predicts the density values as a function of applied compaction pressure.

### **5. Discussion**

Powder metallurgical processing quite often yields materials containing a substantial amount of residual porosity along particle boundaries. Successful utilization of the process, therefore, needs careful control of the deformation, elimination of flash formation and, perhaps the most important, proper densification.

Theories describing the deformation of porous material are enumerated and the changes in density in powder forming process are analyzed with the help of a theoretical and numerical analysis by Bruhns and Sluzalec [2] to model the densification behaviour of porous materials.

These models [3-5] may not be appropriate for the early stage of compaction response, in view of the fact that the inter-particle cohesion of loose powder compact is much less. Out of several models developed in the past, the hyperbolic cap model proposed by Lee and Kim [1] agreed well with the experimental data in the overall density region under cold compaction of Aluminum alloy powder. Since, the processing parameters such as composition, particle distribution, ball to charge ratio, compaction pressure etc., will exhibit significant influence on densification behaviour, it is very important to develop densification models for the alloys under consideration, validate them and then use them to predict appropriate compaction pressure, so as to successfully implement P/M processing.

In this work, the modeling of compressibility test data is carried out by using non-linear regression algorithm, fitting five different sigmoidal models, for various compositions of ball milled and attrition milled alloys separately. Based on the results presented in Table-6, it can be concluded that Richards model emerged as the best fit model, for a good number of ball milled alloys satisfying maximum value of coefficient of correlation and minimum value of standard error of estimate. Further, this model is validated considering the data outside the range of experimentation and found to predict density, within  $\pm$  1 % for ball milled alloys. This is also confirmed by validating Richards model with the data generated from the presentations by Lee and Kim (2002) on Aluminum alloys in cold compaction. This approach is found quite helpful in deciding the compaction pressure for powder metallurgical processing of Al-Pb alloys of various compositions, where there are a number of variants influencing densification behaviour.

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